

## Управляющая программа для микрокомпьютера SX-28 для экспериментов с импульсным разрядом.

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; PRODUCING OF THE DISCHARGE PULSES AND PULSES FOR AD COMBATA.
; For every discharge pulse two pulses for AD combata are produced.
; First at the same time when discharge pulse and second one is shifted.
; Useful pulse is a second pulse. But because there is a noise pulse
; at the time of the begining of discharge which causes acidental runing of AD combata
; we force this pulse of noise by another pulse. These false data
; counting by AD combata will be removed by the C++ program which will processed
; data. It is much more easy way than struggle against nois pulses.
=====
; ===== Assembler directives =====
; uses: SX28AC 2 pages of program memory, 8 banks of RAM, high speed osc.
; operating in turbo mode, with 8-level stack & extended option reg.
; DEVICE SX28L, OSCXTMAX
; DEVICE turbo_stackx_optionx
; ID 'SX_Disch' ;program ID label
; FREQ 50000000
; ===== RESET =====
; RESET reset entry ;set reset/boot address. Input point of the program.
; *****
; SCAN equ rb.7 ; Input, scan signal. High level for the forward scan,
; DisPulse equ rb.6 ; low level for the back scan.
the ; Output, to fire a discharge pulse. These pulses occur after dividing of
; frequency of HeNe laser and expanded in time.
; HeNe equ rb.5 ; Input, HeNe laser. This pin is used for the detection of the edge
interruption. ;
ADPulse equ rb.4 ; Output, pulses for AD combata shifted in time with respect to the
; discharge pulses.
UsedScan equ rb.2 ; Output, SCAN signal to AD. It is needed for the sinchronization of the
; performance of AD and Sx-chip.
; Now it is a trigger for AD combata and signal to handle PC program.
; It is used instead of SCAN line because from on this pin a much less
; pulse noise than on SCAN pin.
; UsedScan output is not used because after 25.10.01 something happened with electronics and SX chip could
not
; drive AD with this signal. This signal was replaced by scan signal in the electic curcits.
; ADready equ rb.0 ; Input, waiting for the start of AD.
; cycles equ -120 ; negative number, which determine the time in SX cycles between next
; RTCC interuption.
; org 8
; divider ds 1 ; the DisPulses occur with a 1:divider ratio of HeNe frquency.
scan ; ShiftCount ds 1 ; number of the HeNe pulses to be skipped after beginning of the forward
; to fire the first discharge pulse. It is a ring counter which takes a
value in
; the range 0 < ShCount < divider-1.
; SkipCount ds 1 ; number of the HeNe pulses between two next discharge pulses.
; It is a ring counter which takes a value in the range 0 < ShCount <
divider-1.
; Cdis ds 1 ; counter responsible for the width of the discharge pulse.
; Diswidth ds 1 ; width of the discharge pulse.
of the ; Cdel ds 1 ; counter responsible for the delay of the AD pulse relative to the start
; discharge pulse.
; ADDelay ds 1 ; delay of the AD pulse.
; CADw ds 1 ; counter responsible for the width of the AD pulse.
; ADwidth ds 1 ; width of the AD pulse.
discharge ; ADpulsewas ds 1 ; flag which determines either or not the AD pulse was at the current
cycle. ; =0 if it was not yet.
; Work1 ds 1
; IsNoisePulse ds 1 ; =1 if there is a first, "noise" pulse for AD combata.
; OneTwoPulses ds 1 ; =1 - two pulses, =0 - one pulse (without "noise" pulse).
; ===== TIMER INTERRUPTION =====
; org 0 ; It must always start at address of the interruption.
; This routine is responsible for the pulse widths and for the starting of the AD shifted pulses.
; snb ADPulse ; is there AD pulse now? AD pulse can be "noise" or
; useful.
; jmp :AD_pulse_width ; Yes. AD pulse exists. Go to manage the pulse widthes.
; snb ADpulsewas.0 ; Was AD pulse already earlier?
; jmp :Dis_pulse_width ; Yes. So let us work with discharge pulse.
; decsz CDel ; No. AD pulse is not yet started.
; jmp :Dis_pulse_width ; So, we must make delay of the AD start.
; ; It is not time to start AD pulse. So let us continue
; ; to work with discharge pulse.
; setb ADPulse ; Is it time to start AD.
; setb ADpulsewas.0
; jmp :Dis_pulse_width ; OK with AD start. Go to discharge pulse.
:AD_pulse_width
; test IsNoisePulse ; is it "noise" pulse?
; jz :not_noise_pulse
; clrb ADPulse ; stop "noise" pulse.
; clr IsNoisePulse
; jmp :Dis_pulse_width ; Go to verify a discharge pulse.
:not_noise_pulse
; decsz CADw ; Is it time to stop AD pulse?
; jmp :Dis_pulse_width ; No.
; clrb ADPulse ; Yes.
:Dis_pulse_width
; test Cdis
; jz :out
; ; It is two old instructions.
; sb DisPulse ; Is a discharge pulse now?
; jmp :out ; No. Go home.
; ; It is 7 new instructions. 13.11.01. They have been included to prevent of the influence of
; the pulse noise to give false disision about existing of the pulse discharge.
; mov Work1, #5
:CheckDis
; snb DisPulse ; Is a discharge pulse now?
; jmp :ContinueDis
; decsz Work1
; jmp :CheckDis
; jmp :out ; No. Go home.
:ContinueDis
; decsz Cdis ; It is time to stop discharge pulse?
; jmp :out ; No. Go home.

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    clr     DisPulse      ; Yes, stop discharge.
;   mov     !option,    %%11001000 ; disable interruption from RTCC.
;out  mov     w,        #cycles
;   reti
; ***** END OF TIMER INTERRUPTION *****
; ===== RESET ENTRY POINT =====
reset_entry PAGE start ;Set page bits and then
start
    clr     rtcc
    mov     !option,    %%11001000 ; disable interruption from RTCC.
; ===== Adjusting of the parameters =====
; All time terms are in the terms between the two RTCC interruptions.
    mov     divider,    #1
    mov     ShiftCount, #1
    mov     Diswidth,   #4 ;#10 ;#4
    mov     ADdelay,    #2 ;#8 ;#2
    mov     ADwidth,    #1
    mov     OneTwoPulses, #1
; *****
; ===== Set B Port options =====
mode     $F ; direction.
mov     !rb,    %%10100001 ; B Port directions, 0=OUT 1=IN.
mode     $A ; rising edges
mov     !rb,    #$00 ; at the HeNe input pin and all other pins.
mode     $9
mov     !rb,    #$00 ; clearing the pending register.
mode     $D ; level
mov     !rb,    #$FF ; TTL
mov     !rb,    #$00 ; B Port low levels
mode     $B
mov     !rb,    %%11111111 ; disable interrupts from port B.
; Next two instructions should decrease of an influence of the noise.
mode     $C ; Schmitt triggers (0).
mov     !rb,    %%01011110
; Next two instructions may be not necessary.
mode     $E
mov     !rb,    %%01111111 ; enable pullup register for SCAN.
; *****
;   clr     IsNoisePulse
; Next block is inserted on 25.10.01
; ===== Waiting for the command from PC that =====
; == Next cycle wait for the start of C++ program which must send high level ==
; == signal on the ADready pin. The C++ program do it with function AD_Out_Aux(1). ==
;what_does_AD_do
sb     ADready ; The chip can go out from this cycle when
jmp    :what_does_AD_do ; PC program put 1 at ADready pin with AD_Out_Aux(1).
; Next two instructions are necessary if a next version of this program will
; use the interruptions from the b port. But they are kept in this version.
mode     $9
mov     !rb,    #$00 ; clearing the pending register.
; *****
; ===== Waiting for the beginning of the forward scan =====
;not_shifted_scan
;   mov     ShiftCount, #1
;   snb     ADready ; Has AD work been finished ? If C++ program is finished
;           ; then SX go to sleep.
;   jmp     :shifted_scan
mode     $B
mov     !rb,    %%11111110 ; enable interruption on rb.0 pin. In the future
;           ; SX wakes up from rb.0 signal which will send by
;           ; the "out(1)" button in C++ program.
mode     $9
mov     !rb,    #$00 ; clearing the pending register.
sleep
;shifted_scan
mov     !option,    %%11001000 ; disable interruption from RTCC.
clr     DisPulse ; Stop discharge.
; =====
mode     $9
; This cycle detects the start of the scan by occurring 1 in the pending bit
; corresponding to the SCAN. This method can be implemented because
; at the thime of the beginning of the scan there is no discharge and, as
; a consequence, no pulse noise.
;start_scan
    clr     w
    mov     !rb, w ; swapping and clearing of the pending bits.
    and     w,    %%10000000
    jz     :start_scan
    setb    UsedScan ; permission for AD to take data. 25.10.01
;           ; This signal triggers AD combata.
;-----
; Another realization of the above part of the program.
; It employ a checking of the high level of the SCAN bit instead of
; checking the corresponding pending bit.
; *****
;start_scan
sb     SCAN
jmp    :start_scan
setb   UsedScan ; permission for AD to take data. 25.10.01
; ===== Skip ShiftCount pulses of HeNe laser =====
; This realization does not work well. The problems in SX chip. It does not work correctly.
;   mov     Work1, ShiftCount
mode     $9
;skip_pulses
;wait_for_pulse ; skip HeNe pulses ShiftCount times.
;           ; waiting for the next HeNe pulse.
    clr     w
    mov     !rb, w ; swapping and clearing of the pending bits.
    and     w,    %%00100000
    jz     :wait_for_pulse
    decsz   Work1
    jmp    :skip_pulses
;-----
; Another realization of the above part of the program
;   mov     Work1, #1 ; experiment.
;   mov     Work1, #24 ; experiment.
;
;   mov     Work1, ShiftCount
;skip_pulses ; skip HeNe pulses ShiftCount times.
;high_HeNe
;   snb     HeNe
;   jmp    :high_HeNe
;low_HeNe

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sb          HeNe
jmp         :low_HeNe
decsz     work1
jmp         :skip_pulses
; *****
;===== Timer enable =====
:fire_discharge
clr       rtcc          ; clear timer.
mov       !option,    %%10001000 ; enable interruption from RTCC.
; *****
;===== Fire discharge pulse =====
mov       SkipCount,  divider
test     OneTwoPulses ; if zero then a noise pulse is not needed.
jnz     :noispulse
mov       rb,    %%01000100 ; setting only the DisPulse bit
; and leaving UsedScan at high level.
jmp      :ok
:noispulse
mov       rb,    %%01010100 ; setting the DisPulse bit and a "noise" AdPulse
; and leaving UsedScan at high level.
:ok
mov       IsNoisePulse, #1 ; "noise" pulse start
mov       Cdis,  DisWidth
inc       Cdis
mov       Cdel,  ADDelay
inc       Cdel
mov       CADw,  ADwidth
inc       CADw
clr      ADpulsewas
mov       rtcc,  #$FE ; initialization of the timer to quickly start the forming
; AD pulse. The number #$FE results rtcc interuption after
; next two instruction cycles. And therefore a counting of
; the all delays and widths starts almost immediately after
; beginning of the discharge pulse (in the interuption
; procedure.
; *****
;===== Varification of a forward scan =====
:skip_pulses_1
sb          SCAN
jmp         :new_scan_prep ; forward scan is over, Go to prepare a new scan.
; *****
;===== Waiting for the next HeNe pulse =====
; It should be noted that, first, divider=1 means no skipping of the HeNe pulses
; and, second, at the moment of the start of the bellow loop to count skipped
; HeNe pulses the discharge has already burned.
;-----
; This realization of the skipping of the HeNe pulses does not
; work because pending bits in B port are loos in the interuption
; routine
mode      $9
:wait_for_pulse_1
clr       w
mov       !rb,    w ; swapping and clearing of the pending bits.
and      w,    %%00100000
jz       :wait_for_pulse_1
decsz   SkipCount
jmp      :skip_pulses_1
jmp      :fire_discharge ; a needed number of HeNe pulses is skipped so let us
; immediatly fire discharge at the present HeNe pulse.
;-----
; Another realization of the above part of the program which
; produces the skipping of a needed number of HeNe pulses.
:high
snb      HeNe
jmp      :high
:low
sb       HeNe
jmp      :low
decsz   SkipCount
jmp      :skip_pulses_1
jmp      :fire_discharge ; a needed number of HeNe pulses is skipped so let us
; immediatly fire discharge at the present HeNe pulse.
; *****
;===== Preparation to next scan =====
:new_scan_prep
mov      !option,    %%11001000 ; disable interruption from RTCC.
mode     $9
mov      !rb,    #0 ; clearing the pending bits. They could contain the old data.
mov      rb,    %%00000000 ; stop all pulses
;
; clrb   UsedScan ; prohibition for AD to take data. 25.10.01
; clrb   DisPulse ; stop discharge pulse.
; clrb   ADPulse ; stop AD pulse.
; inc    ShiftCount
;
; cja    ShiftCount,divider,:not_shifted_scan
; jmp    :shifted_scan
; jmp    :not_shifted_scan
; *****
end

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